## Visualizing High-Dimensional Vectors

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The next two examples are drawn from:
http://setosa.io/ev/principal-component-analysis/

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How to visualize these for




## Visualizing High-Dimensional Vectors



How to visualize these for comparison? ${ }^{800}$

## 400 -

200 -

Using our earlier analysis:
Compare pairs of food items across locations
(e.g., scatter plot of cheese vs cereals consumption)




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How to visualize these for comparison? ${ }^{800}$ 400 200

Using our earlier analysis:
Compare pairs of food items across locations
(e.g., scatter plot of cheese vs cereals consumption)

But unclear how to compare the locations (England, Wales, Scotland, N. Ireland)!



## The issue is that as humans we can only really visualize up to 3 dimensions easily

Goal: Somehow reduce the dimensionality of the data preferably to 1, 2, or 3

## Principal Component Analysis (PCA)

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How to project 2D data down to 1D?


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Simplest thing to try: flatten to one of the red axes

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Simplest thing to try: flatten to one of the red axes
(We could of course flatten to the other red axis)

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 How to projoct 2D data dominn to 1D?How to rotate 2D data so 1st axis has most variance


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 How to projoct an - data dominto 1D?How to rotate 2D data so 1st axis has most variance


The idea of PCA actually works for 2D $\rightarrow$ 2D as well (and just involves rotating, and not "flattening" the data)

2nd green axis chosen to be $90^{\circ}$ ("orthogonal") from first green axis

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- Finds top $k$ orthogonal directions that explain the most variance in the data


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- Finds top $k$ orthogonal directions that explain the most variance in the data
- 1st component: explains most variance along 1 dimension
- 2nd component: explains most of remaining variance along next dimension that is orthogonal to 1st dimension
- ...
- "Flatten" data to the top $k$ dimensions to get lower dimensional representation (if $k<$ original dimension)


## Principal Component Analysis (PCA)

3D example from:
http://setosa.io/ev/principal-component-analysis/

## Principal Component Analysis (PCA)

Demo

PCA reorients data so axes explain variance in "decreasing order" $\rightarrow$ can "flatten" (project) data onto a few axes that captures most variance


Image source: http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcI/AAAAAAAAGp8/ Hea8UtE_1c0/s1600/Blog\%2B1\%2BIMG_1821.jpg

## 2D Swiss Roll



## 2D Swiss Roll



PCA would just flatten this thing and lose the information that the data actually lives on a 1D line that has been curved!


Image source: http://4.bp.blogspot.com/-USQEgoh1jCU/VfncdNOETcI/AAAAAAAAGp8/ Hea8UtE_1c0/s1600/Blog\%2B1\%2BIMG_1821.jpg

## 2D Swiss Roll



## 2D Swiss Roll



2D Swiss Roll


2D Swiss Roll


## 2D Swiss Roll



## 2D Swiss Roll

This is the desired result

## 3D Swiss Roll



## 3D Swiss Roll



Projecting down to any 2D plane puts points that are far apart close together!

## 3D Swiss Roll



Goal: Low-dimensional representation where similar colored points are near each other (we don't actually get to see the colors)

## Manifold Learning

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- Nonlinear dimensionality reduction (in contrast to PCA which is linear)


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1. Zoom in on any point (say, x)

## Manifold Learning

- Nonlinear dimensionality reduction (in contrast to PCA which is linear)
- Find low-dimensional "manifold" that the data live on


Basic idea of a manifold:

1. Zoom in on any point (say, x)
2. The points near $x$ look like they're in a lower-dimensional

Euclidean space
(e.g., a 2D plane in Swiss roll)

## Do Data Actually Live on Manifolds?

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Image source: http://www.columbia.edu/~jwp2128/Images/faces.jpeg

## Do Data Actually Live on Manifolds?


$\square$

Phillip Isola, Joseph Lim, Edward H. Adelson. Discovering States and Transformations in Image Collections. CVPR 2015.

## Do Data Actually Live on Manifolds?



Image source: http://www.adityathakker.com/wp-content/uploads/2017/06/word-embeddings-994x675.png

## Do Data Actually Live on Manifolds? <br> 

Mnih, Volodymyr, et al. Human-level control through deep reinforcement learning. Nature 2015.

## Manifold Learning with Isomap



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Step 1: For each point, find its nearest neighbors, and
build a road ("edge") between them

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Step 1: For each point, find its nearest neighbors, and build a road ("edge") between them

(e.g., find closest 2
neighbors per point and add edges to them)

Step 2: Compute shortest distance from each point to every other point where you're only allowed to travel on the roads
Step 3: It turns out that given all the distances between pairs of points, we can compute what the points should be (the algorithm for this is called multidimensional scaling)

## Isomap Calculation Example

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## ${ }_{E}^{\text {Cob }}$

## Isomap Calculation Example



Build "symmetric 2-NN" graph (add edges for each point to its 2 nearest neighbors)

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## Isomap Calculation Example

In orange: road lengths
2 nearest neighbors of $A$ : $B, C$


2 nearest neighbors of $B$ : $A, C$
2 nearest neighbors of $C$ : $B, D$
2 nearest neighbors of D : C, E
2 nearest neighbors of $E: C, D$
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Build "symmetric 2-NN" graph (add edges for each point to its 2 nearest neighbors)

Shortest distances between every point to every other point where we are only allowed to travel along the roads

|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| A |  |  |  | E |
| B |  |  |  |  |
| C |  |  |  |  |
| D |  |  |  |  |
| E |  |  |  |  |

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|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 |  |  |  |
| B |  | 0 |  |  |
| C |  |  | 0 |  |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | $D$ |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 |  |  |
| B |  | 0 | 5 |  |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | $D$ |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 |  |
| B |  | 0 | 5 |  |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 |
| B |  | 0 | 5 |  |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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Shortest distances between every point to every other point where we are only allowed to travel along the roads

|  | A | B | C | $D$ |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 |
| B |  | 0 | 5 | 16 |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 |
| B |  | 0 | 5 | 10 |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | $D$ |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 |
| B |  | 0 | 5 | 10 |
| C |  |  | 0 | 5 |
| D |  |  |  | 0 |
| E |  |  |  |  |

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|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 |
| B | 5 | 0 | 5 | 10 |
| C | 8 | 5 | 0 | 5 |
| D | 13 | 10 | 5 | 0 |
| E | 16 | 13 | 8 | 5 |

## Isomap Calculation Example

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Shortest distances between every point to every other point where we are only allowed to travel along the roads

|  | A | B | C | D | E |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 | 16 |
| B | This matrix gets fed into <br> multidimensional scaling to get |  |  |  |  |
| C | 1D version of A, B, C, D, E |  |  |  |  |

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2 nearest neighbors of $B$ : $A, C$
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|  | A | B | C | D | E |
| :---: | :---: | :---: | :---: | :---: | :---: |
| A | 0 | 5 | 8 | 13 | 16 |
| B | This matrix gets fed into |  |  |  |  |
| multidimensional scaling to get |  |  |  |  |  |
| C | 1D version of A, B, C, D, E |  |  |  |  |
| D | The solution is not unique! |  |  |  |  |
| E | 16 | 13 | 8 | 5 | 0 |

## Isomap Calculation Example

Multidimensional scaling demo

## 3D Swiss Roll Example



Joshua B. Tenenbaum, Vin de Silva, John C. Langford. A Global Geometric Framework for Nonlinear Dimensionality Reduction. Science 2000.

## Some Observations on Isomap



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In general: try different parameters for nearest neighbor graph construction when using Isomap + visualize

## t-SNE

(t-distributed stochastic neighbor embedding)
t-SNE High-Level Idea \#1

## t-SNE High-Level Idea \#1

- Don't use deterministic definition of which points are neighbors


## t-SNE High-Level Idea \#1

- Don't use deterministic definition of which points are neighbors
- Use probabilistic notation instead


## t-SNE High-Level Idea \#1

- Don't use deterministic definition of which points are neighbors
- Use probabilistic notation instead

t-SNE High-Level Idea \#2


## t-SNE High-Level Idea \#2

- In low-dim. space (e.g., 1D), suppose we just randomly assigned coordinates as a candidate for a low-dimensional representation for $A, B, C, D, E$ (I'll denote them with primes):


## t-SNE High-Level Idea \#2

- In low-dim. space (e.g., 1D), suppose we just randomly assigned coordinates as a candidate for a low-dimensional representation for A, B, C, D, E (I'll denote them with primes):



## t-SNE High-Level Idea \#2

- In low-dim. space (e.g., 1D), suppose we just randomly assigned coordinates as a candidate for a low-dimensional representation for A, B, C, D, E (I'll denote them with primes):

- With any such candidate choice, we can define a probability distribution for these low-dimensional points being similar


## t-SNE High-Level Idea \#2

- In low-dim. space (e.g., 1D), suppose we just randomly assigned coordinates as a candidate for a low-dimensional representation for A, B, C, D, E (I'll denote them with primes):

- With any such candidate choice, we can define a probability distribution for these low-dimensional points being similar



## t-SNE High-Level Idea \#3

## t-SNE High-Level Idea \#3

- Keep improving low-dimensional representation to make the following two distributions look as closely alike as possible


## t-SNE High-Level Idea \#3

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- Keep improving low-dimensional representation to make the following two distributions look as closely alike as possible



## t-SNE High-Level Idea \#3

- Keep improving low-dimensional representation to make the following two distributions look as closely alike as possible



## t-SNE High-Level Idea \#3

- Keep improving low-dimensional representation to make the following two distributions look as closely alike as possible


Thisodistribution changes as we move around low-dim. points


## Manifold Learning with t-SNE

Demo

## Technical Detail for t-SNE

Fleshing out high level idea \#1
Suppose there are $n$ high-dimensional points $x_{1}, x_{2}, \ldots, x_{n}$
For a specific point $i$, point $i$ picks point $j(\neq i)$ to be a neighbor with probability:

$$
p_{j \mid i}=\frac{\exp \left(-\frac{\left\|x_{i}-x_{i}\right\|^{2}}{2 \sigma_{i}^{2}}\right)}{\sum_{k \neq i} \exp \left(-\frac{\left\|x_{i}-x_{k}\right\|^{2}}{2 \sigma_{i}^{2}}\right)}
$$

$\sigma_{i}$ (depends on i) controls the probability in which point $j$ would be picked by $i$ as a neighbor (think about when it gets close to 0 or when it explodes to $\infty$ )
$\sigma_{i}$ is controlled by a knob called 'perplexity'
(rough intuition: it is like selecting small vs large neighborhoods for Isomap)
Points $i$ and $j$ are "similar" with probability: $\quad p_{i, j}=\frac{p_{j \mid i}+p_{i \mid j}}{2 n}$
This defines the earlier blue distribution

## Technical Detail for t-SNE

Fleshing out high level idea \#2
Denote the $n$ low-dimensional points as $x_{1}{ }^{\prime}, x_{2}{ }^{\prime}, \ldots, x_{n}{ }^{\prime}$
Low-dim. points $i$ and $j$ are "similar" with probability: $q_{i, j}=\frac{\frac{1}{1+\left\|x_{i}^{\prime}-x_{j}^{\prime}\right\|^{2}}}{\sum_{k \neq m} \frac{1}{1+\| \|_{k}^{x_{k}}-x_{m}^{\prime} \|^{2}}}$
This defines the earlier green distribution

Fleshing out high level idea \#3
Use gradient descent (with respect to $q_{i, j}$ ) to minimize:

$$
\sum_{i \neq j} p_{i, j} \log \frac{p_{i, j}}{q_{i, j}}
$$

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is a way of debugging data analysis!


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- PCA and t-SNE are good candidates for methods to try first
- If you have good reason to believe that only certain features matter, of course you could restrict your analysis to those!

